# Central Algorithmic Techniques 

Iterative Algorithms

## Code Representation of an Algorithm

class InsertionSortAlgorithm extends SortAlgorithm \{ void sort(int a[]) throws Exception \{

$$
\begin{aligned}
& \text { for (int } \mathrm{i}=1 ; \mathrm{i}<\text { a.length; } \mathrm{i}++)\{ \\
& \qquad \begin{array}{l}
\text { int } \mathrm{j}=\mathrm{i} ; \\
\text { int } \mathrm{B}
\end{array}=\mathrm{a}[\mathrm{i}] ; \\
& \text { while }((\mathrm{j}>0) \& \&(\mathrm{a}[\mathrm{j}-1]>B))\{ \\
& \quad \mathrm{a}[\mathrm{j}]=\mathrm{a}[\mathrm{j}-1] ; \\
& \mathrm{j}--;\} \\
& \mathrm{a}[\mathrm{j}]=\mathrm{B} ; \quad
\end{aligned}
$$

# Code Representation of an Algorithm 

## Pros:

- Runs on computers
- Precise and succinct


## Cons:

- I am not a computer
- I need a higher level of intuition.
- Prone to bugs
- Language dependent


## Two Key Types of Algorithms

- Iterative Algorithms
- Recursive Algorithms


## Iterative Algorithms

## Take one step at a time

 towards the final destinationloop (done)<br>take step<br>end loop

## Loop Invariants

A good way to structure many programs:

- Store the key information you currently know in some data representation.
- In the main loop,
- take a step forward towards destination
- by making a simple change to this data.


## The Getting to School Problem



## Problem Specification

- Pre condition: location of home and school
- Post condition: Traveled from home to school



## General Principle

- Do not worry about the entire computation.
- Take one step at a time!



## A Measure of Progress



## Safe Locations

- Algorithm specifies from which locations it knows how to step.



## Loop Invariant

- "The computation is presently in a safe location."
- May or may not be true.



## Defining Algorithm

- From every safe location, define one step towards school.



## Take a step

- What is required of this step?



## Maintain Loop Invariant

- If the computation is in a safe location, it does not step into an unsafe one.
- Can we be assured that the computation will always be in a safe location?


No. What if it is not initially true?

## Establishing Loop Invariant

From the Pre-Conditions on the input instance we must establish the loop invariant.


## Maintain Loop Invariant

- Can we be assured that the computation will always be in a safe location?
- By what principle?


## Maintain Loop Invariant

- By Induction the computation will always be in a safe location.




## Ending The Algorithm

- Define Exit Condition
- Termination: With sufficient progress, the exit condition will be met.
- When we exit, we know
- exit condition is true
- loop invariant is true
from these we must establish the post conditions.

\&


## Designing an Algorithm

| Define Problem | Define Loop Invariants | Define Measure of Progress |
| :---: | :---: | :---: |
| Define Step | Define Exit Condition | Maintain Loop Inv |
| Make Progress | Initial Conditions <br> 21 | Ending |

## Simple Example

Insertion Sort Algorithm

## Code Representation of an Algorithm

```
class InsertionSortAlgorithm extends SortAlgorithm {
    void sort(int a[]) throws Exception {
    for (int i = 1; i < a.length; i++) {
        int j = i;
        int B = a[i];
        while ((j>0) && (a[j-1]>B)) {
        a[j] = a[j-1];
        j--; }
    a[j] = B;
    }}

\section*{Higher Level Abstract View Representation of an Algorithm}


\section*{Designing an Algorithm}


\section*{Problem Specification}
- Precondition: The input is a list of \(n\) values with the same value possibly repeated.
- Post condition: The output is a list consisting of the same \(n\) values in non-decreasing order.


> 14,23,25,30,31,52,62,79,88,98

\section*{Define Loop Invariant}
- Some subset of the elements are sorted
-The remaining elements are off to the side.


\section*{Defining Measure of Progress}


\section*{Define Step}
- Select arbitrary element from side.
- Insert it where it belongs.


\section*{Making progress while Maintaining the loop invariant}


\section*{Beginning \& Ending}


to school
\(14,23,25,30,31,52,62,79,88,98\)


\section*{Running Time}

Inserting an element into a list of size i takes \(\theta\) (i) time.
\[
\text { Total }=1+2+3+\ldots+n=\theta\left(n^{2}\right)
\]


\title{
Ok \\ I know you knew Insertion Sort
}

But hopefully you are beginning to appreciate
Loop Invariants
for describing algorithms

\section*{Assertions}

\section*{in Algorithms}

\section*{Purpose of Assertions}

\section*{Useful for}
- thinking about algorithms
- developing
- describing
- proving correctness

\section*{Definition of Assertions}

An assertion is a statement about the current state of the data structure that is either true or false.
eg. the amount in your bank account is not negative.

\section*{Definition of Assertions}

It is made at some particular point during the execution of an algorithm.

If it is false, then something has gone wrong in the logic of the algorithm.

\section*{Definition of Assertions}

An assertion is not a task for the algorithm to perform.

It is only a comment that is added for the benefit of the reader.

\section*{Specifying a Computational Problem}

Example of Assertions
- Preconditions: Any assumptions that must be true about the input instance.
- Postconditions: The statement of what must be true when the algorithm/program returns..

\section*{Definition of Correctness}

\section*{<PreCond> \& <code> \(\Rightarrow\) <PostCond>}

If the input meets the preconditions,
then the output must meet the postconditions.

If the input does not meet the preconditions, then nothing is required.

\section*{An Example:}
<assertion \({ }_{0}\) A Sequence of Assertions
if( <condition \({ }_{1}\) ) then
code \(_{\text {<1, true }}\)
else
code \(_{<1 \text {,false> }}\)
end if
<assertion \({ }_{1}\) >
:
<assertion \({ }_{r-1}>\)
if( <condition \({ }_{r}\) ) then code \(_{\text {<r,true> }}\)
else
code \(_{\text {<r,false> }}\)
end if
<assertion> \({ }_{r}\) >

\section*{Definition of Correctness}
\(<\) assertion \(_{0}>\)
any \(<\) conditions \(>\square<\) assertion \(_{\mathrm{r}}>\) code

Must check \(2^{\text {r }}\) different -settings of <conditions> -paths through the code.
Is there a faster way?
<assertion \({ }_{0}>\)
if \(\left(<\right.\) condition \(\left._{1}>\right)\) then code \(_{\text {<1,true> }}\)
else
code \(_{<1, \text { false }}\)
end if
<assertion \({ }_{1}\) >
:
<ass̊ertion \({ }_{r-1}\) >
if( <condition \({ }_{r}>\) ) then code \(_{\text {<r,true> }}\)
else code \(_{\text {<r,false> }}\)
end if
<assertion> \({ }_{r}\) >

\section*{An Example: \\ \\ A Sequence of Assertions} \\ \\ A Sequence of Assertions}

\section*{Step 1}
\(<\) assertion \(_{0}>\)
\(<\) condition \(_{1}>\)
 code \(_{<1 \text {,true }}\)
\(<\) assertion \(_{0}>\)
\(\neg<\) condition \(_{1}>\)
 code \(_{<1 \text {,false }>}\)
<assertion \({ }_{0}\) >
if( <condition \({ }_{1}>\) ) then code \(_{\text {<1, true> }}\)
else
code \(_{<1 \text {,false> }}\)
end if

if( <condition \({ }_{r}\) ) then code \({ }_{\text {<r,true> }}\)
else
code \(_{<r, \text { false> }}\)
end if
<assertion \({ }_{r}\) >

\section*{An Example: \\ A Sequence of Assertions}

\section*{Step 2}
\(<\) assertion \(_{1}>\)
\(<\) condition \(_{2}>\) code \(_{<2, \text { true }}\)
\(<\) assertion \(_{1}>\)
\(\neg<\) condition \(_{2}>\)
 code \(_{<2 \text {,false }>}\)

\section*{An Example:}
<assertion \({ }_{0}\) >
if( <condition \({ }_{1}>\) ) then code \(_{\text {<1, true> }}\)
else
code \(_{\text {<1,false> }}\)
end if
<assertion \({ }_{1}>\)
\(\vdots\)
<assertion \({ }_{r-1}>\)
if \(\left(\right.\) <condition \(_{r}>\) ) then code \(_{\text {<r,true> }}\)
else code \(_{\text {<r,false> }}\) end if
<assertion> \({ }_{r}\) >
\(<\) assertion \(_{\text {r- }}>\)
\(<\) condition \(_{r}>\) code \(_{<\mathrm{r}, \text { true }}>\)
\(<\) assertion \(_{\text {r- }}>\)
\(\neg<\) condition \(_{\mathrm{r}}>\) code \(_{<\text {r,false }}>\)

\section*{Step r}


\(<\) assertion \(_{\mathrm{r}}>\)

\section*{A Sequence of Assertions}
<assertion \({ }_{0}\) >
if( <condition \({ }_{1}>\) ) then
code \(_{\text {<1,true> }}\)
else
code \(_{<1 \text {,false }}\)
end if

\section*{Step r}
\(<\) assertion \(_{\mathrm{r}-1}>\)
\(<\) condition \(_{\mathrm{r}}>\)
code \(_{<\text {r,true }}\)
<assertion \({ }_{1}>\)
\(\vdots\)
<assertion \({ }_{r-1}>\)
if \((\) <condition \(\gg\) ) then code \(_{\text {<r,true> }}\)
else
code \(_{<r, \text { false> }}\)
end if
<assertion> \({ }^{\text {> }}\)

\(<\) assertion \(_{\text {r- }}>\)
\(\neg<\) condition \(_{\mathrm{r}}>\)

\(<\) assertion \(_{\mathrm{r}}>\) code \(_{<\text {r,false }}>\)

\section*{Another Example: A Loop}

\section*{<preCond>}
codeA
loop

\section*{<loop-invariant>} exit when <exit Cond> codeB
endloop
Type of Algorithm:
- Iterative

Type of Assertion:
- Loop Invariants
codeC
<postCond>

\title{
Iterative Algorithms Loop Invariants
}

\section*{<preCond>}
codeA
loop

\section*{<loop-invariant>} exit when <exit codeB
endloop
codeC
<postCond>

\section*{Iterative Algorithms Loop Invariants}
<preCond>
codeA
loop

\section*{<loop-invariant>}
exit when <exit Cond> Definition of Correctness codeB endloop
codeC
<postCond>


\author{
How is this proved?
}

\section*{Iterative Algorithms Loop Invariants}

\section*{<preCond>}
codeA
loop
<loop-invariant> exit when <exit Cond> codeB

\section*{Definition of Correctness}
endloop
codeC
<postCond>


The computation may go around the loop an arbitrary number of times.

Is there a faster way?

\section*{Iterative Algorithms Loop Invariants}

\section*{<preCond>}
codeA
loop

\section*{<loop-invariant>}
exit when <exit Cond>
Step 0 codeB
endloop
codeC
<postCond>
<preCond>
codeA

\section*{Iterative Algorithms Loop Invariants}

\section*{codeA \\ loop}
<preCond>

\section*{<loop-invariant>}
exit when <exit Cond> Step 1 \(\begin{array}{ll}\begin{array}{c}\text { CodeB } \\ \text { endloop } \\ \text { codeC }\end{array} & \begin{array}{l}\text { <loop-invariant> } \\ \text {-<exit Cond> } \\ \text { codeB }\end{array}\end{array}\) <loop-invariant
<postCond>

\section*{Iterative Algorithms Loop Invariants}

\section*{<preCond> \\ codeA \\ loop}
<logp-invariant>


\section*{Iterative Algorithms Loop Invariants}

\section*{<preCond> \\ codeA \\ loop}
<loop-invariant>


\section*{Iterative Algorithms Loop Invariants}
<preCond>
codeA
loop
endloop
codeC
<postCond>

Step i
<loop-invariant>
«exit Cond» \(\square\) <loop-invariant codeB

All these steps are the same and therefore only need be done once!

\section*{Iterative Algorithms Loop Invariants}

\section*{codeA \\ loop}
<preCond>
<loop-invariant>
exit when zexit Cond> Last Step
codeB endloop
<loop-invariant>
<exit Cond>
\(\square\) <postCond> codeC

\section*{Partial Correctness}

Establishing Loop Invariant

<preCond>
codeA


Maintaining Loop Invariant

<loop-invariant>
-eexit Cond>
codeB


Clean up loose ends

<loop-invariant>
<exit Cond> codeC


Proves that IF the program terminates then it works
\[
\text { <PreCond }>\&<\text { code }>56 \text { PostCond }>
\]

\title{
Algorithm Termination
}

\section*{Measure of progress}


\section*{Algorithm Correctness}

\section*{Partial Correctness \\ + Termination}


\section*{Correctness}

\section*{Designing Loop Invariants}

Coming up with the loop invariant is the hardest part of designing an algorithm.

It requires practice, perseverance, and insight.


\section*{Yet from it \\ the rest of the algorithm follows easily}

\section*{Don't start coding}

\section*{You must design a working algorithm first.}


Exemplification:
Try solving the problem on small input examples.


\section*{Start with Small Steps}

What basic steps might you follow to make some kind of progress towards the answer?

Describe or draw a picture of what the data structure might look like after a number of these steps.


\section*{Picture from the Middle}

\section*{Leap into the middle of the algorithm.}

\section*{What would you like your data structure to look like when you are half done?}


\section*{Ask for 100\%}

\section*{Pretend that a genie has granted your wish.}
- You are now in the middle of your computation and your dream loop invariant is true.


\section*{Ask for 100\%}

\section*{Maintain the Loop Invariant:}
- From here, are you able to take some computational steps that will make progress while maintaining the loop invariant?


\section*{Ask for 100\%}
- If you can maintain the loop invariant, great.
- If not,
- Too Weak: If your loop invariant is too weak, then the genie has not provided you with everything you need to move on.
- Too Strong: If your loop invariant is too strong, then you will not be able to establish it initially or maintain it.

\section*{Differentiating between Iterations}
\(\mathrm{x}=\mathrm{x}+2\)
- Meaningful as code
- False as a mathematical statement
\(x^{\prime}=x_{i}=\) value at the beginning of the iteration
\(x^{\prime \prime}=x_{i+1}=\) new value after going around the loop one more time.
\(x^{\prime \prime}=x^{\prime}+2\)
- Meaningful as a mathematical statement

\title{
Loop Invariants \\ for \\ Iterative Algorithms
}

Three

\author{
Search Examples
}

\section*{Define Problem: Binary Search}
- PreConditions
- Key 25
- Sorted List
\begin{tabular}{|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|}
\hline 3 & 5 & 6 & 13 & 18 & 21 & 21 & 25 & 36 & 43 & 49 & 51 & 53 & 60 & 72 & 74 & 83 & 88 & 91 & 95 \\
\hline
\end{tabular}
- PostConditions
- Find key in list (if there).
\begin{tabular}{|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|}
\hline 3 & 5 & 6 & 13 & 18 & 21 & 21 & 25 & 36 & 43 & 49 & 51 & 53 & 60 & 72 & 74 & 83 & 88 & 91 & 95 \\
\hline
\end{tabular}

\section*{Define Loop Invariant}
- Maintain a sublist.
- If the key is contained in the original list, then the key is contained in the sublist.
key 25
\begin{tabular}{|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|}
\hline 3 & 5 & 6 & 13 & 18 & 21 & 21 & 25 & 36 & 43 & 49 & 51 & 53 & 60 & 72 & 74 & 83 & 88 & 91 & 95 \\
\hline
\end{tabular}

\section*{Define Step}
- Make Progress
- Maintain Loop Invariant

key 25
\begin{tabular}{|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|}
\hline 3 & 5 & 6 & 13 & 18 & 21 & 21 & 25 & 36 & 43 & 49 & 51 & 53 & 60 & 72 & 74 & 83 & 88 & 91 & 95 \\
\hline
\end{tabular}

\section*{Define Step}
- Cut sublist in half.
- Determine which half the key would be in.
- Keep that half.


\section*{Define Step}
- It is faster not to check if the middle element is the key.
- Simply continue.


\section*{Make Progress}
- The size of the list becomes smaller.



\section*{Initial Conditions}
key 25
\begin{tabular}{|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|}
\hline 3 & 5 & 6 & 13 & 18 & 21 & 21 & 25 & 36 & 43 & 49 & 51 & 53 & 60 & 72 & 74 & 83 & 88 & 91 & 95 \\
\hline
\end{tabular}
- The sublist is the entire original list.

- If the key is contained in the original list,
then the key is contained in the sublist.

\section*{Ending Algorithm}

- If the key is contained in the original list,
then the key is contained in the sublist.
- Sublist contains one element.
- If the key is contained in the original list, then the key is at this location.

\section*{If key not in original list}
- If the key is contained in the original list, then the key is contained in the sublist.
- Loop invariant true, even if the key is not in the list.
101011
\begin{tabular}{|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|}
\hline 3 & 5 & 6 & 13 & 18 & 21 & 21 & 25 & 36 & 43 & 49 & 51 & 53 & 60 & 72 & 74 & 83 & 88 & 91 & 95 \\
\hline
\end{tabular}
- If the key is contained in the original list, then the key is at this location.
- Conclusion still solves the problem.
Simply check this one location for the key.

\section*{Running Time}

The sublist is of size \(n, n / 2, n / 4, n / 8, \ldots, 1\)
Each step \(\theta\) (1) time.
Total \(=\theta(\log n)\)


\section*{BinarySearch(A[1..n],key)}
<precondition»: A[1..n] is sorted in non-decreasing order
<postcondition>: If key is in A[1..n], algorithm returns its location
\(p=1, q=n\)
while \(q>p\)
< loop-invariant>: If key is in A[1..n], then key is in A[p..q]
\(\operatorname{mid}=\left\lfloor\frac{p+q}{2}\right\rfloor\)
if key \(\leq A[\) mid \(]\)
\(q=\) mid
else
\[
p=m i d+1
\]
end
end
if key \(=A[p]\)
return( \(p\) )
else
return("Key not in list")
end

\section*{Algorithm Definition Completed}
\begin{tabular}{|c|c|c|}
\hline Define Problem & Define Loop Invariants & Define Measure of Progress \\
\hline Define Step & Define Exit Condition & Maintain Loop Inv \\
\hline Make Progress & \begin{tabular}{l}
Initial Conditions \\
80
\end{tabular} & Ending \\
\hline
\end{tabular}

\section*{BinarySearch(A[1..n],key)}
<precondition»: A[1..n] is sorted in non-decreasing order
<postcondition>: If key is in A[1..n], algorithm returns its location
\(p=1, q=n\)
while \(q>p\)
< loop-invariant>: If key is in A[1..n], then key is in A[p..q]
\(\operatorname{mid}=\left\lfloor\frac{p+q}{2}\right\rfloor\)
if key \(\leq A[\) mid \(]\)
\(q=\) mid
else
\[
p=m i d+1
\]
end
end
if key \(=A[p]\)
return( \(p\) )
else
return("Key not in list")
end

\section*{Simple, right?}
- Although the concept is simple, binary search is notoriously easy to get wrong.
- Why is this?


\section*{The Devil in the Details}
- The basic idea behind binary search is easy to grasp.
- It is then easy to write pseudocode that works for a 'typical' case.
- Unfortunately, it is equally easy to write pseudocode that fails on the boundary conditions.

\section*{The Devil in the Details}

\author{
if key \(\leq A[\) mid \(]\) \\ \(q=\mathrm{mid}\) \\ else \\ \(p=m i d+1\) \\ end
}


What condition will break the loop invariant?

\section*{The Devil in the Details}


Code: key \(\geq A[\) mid \(] \rightarrow\) select right half Bug!!

\section*{The Devil in the Details}
\begin{tabular}{lr} 
if key \(\leq A[\mathrm{mid}]\) & if key \(<A[\mathrm{mid}]\) \\
\(q=\) mid & \(q=\operatorname{mid}-1\) \\
else & else \\
\(\quad p=\) mid +1 & \(p=\) mid \\
end & end
\end{tabular}

OK
OK


Not OK!!

\section*{The Devil in the Details}
\[
\operatorname{mid}=\left\lfloor\frac{p+q}{2}\right\rfloor \quad \text { or } \quad \operatorname{mid}=\left\lceil\frac{p+q}{2}\right\rceil
\]


Shouldn't matter, right? Select mid \(=\left\lceil\frac{p+q}{2}\right\rceil\)

\section*{The Devil in the Details}


\section*{The Devil in the Details}


\section*{The Devil in the Details}


If key \(\leq\) mid, \(\quad\) If key \(>\) mid, then key is in then key is in left half. right half.

\section*{The Devil in the Details}
\begin{tabular}{ll}
\(\operatorname{mid}=\left|\frac{p+q}{2}\right|\) & mid \(=\left[\frac{p+q}{2}\right\rceil\) \\
if key \(\leq A[\mathrm{mid}]\) & if key<A[mid \(]\) \\
\(q=\) mid & \(q=\) mid -1 \\
else & else \\
\(\quad p=\) mid +1 & \(p=\) mid \\
end & end
\end{tabular}

OK
\(\operatorname{mid}=\left\lceil\frac{p+q}{2}\right\rceil\)
if key < \(A[\mathrm{mid}]\)
\[
q=\operatorname{mid}-1
\]
else
end
OK


Not OK!!

\section*{How Many Possible Algorithms?}
\[
\begin{aligned}
& \operatorname{mid}=\left|\frac{p+q}{2}\right| \\
& \text { if key } \leq A[\mathrm{mid}] \\
& q=\text { or mid }=\left[\left.\frac{p+q}{2} \right\rvert\, \text { or } \mathrm{mey}<A[\mathrm{mid}]\right. \text { ? } \\
& \text { else } \\
& \quad p=\text { mid }+1 \\
& \text { end } \quad \text { or } q=\text { mid }-1 \\
& \text { else } \\
& \text { end } p=\text { mid }
\end{aligned}
\]

\section*{Alternative Algorithm: Less Efficient but More Clear}
```

BinarySearch(A[1..n],Key)
<precondition>: A[1..n] is sorted in non-decreasing order
<postcondition>: If key is in A[1..n], algorithm returns its location
p=1,q=n
while q>p
<loop-invariant>: If key is in A[1..n], then key is in A[p..q]
mid = <br>frac{p+q}{2}}
if key = A[mid]
return(mid)
elseif key < A[mid]
q=mid -1
else
p=mid +1
end
end
if key = A[p]
return(p)
else
return("Key not in list")
end

```

\section*{Moral}
- Use the loop invariant method to think about algorithms.
- Be careful with your definitions.
- Be sure that the loop invariant is always maintained.
- Be sure progress is always made.
- Having checked the 'typical' cases, pay particular attention to boundary conditions and the end game.

\title{
Loop Invariants for \\ Iterative Algorithms
}

A Second
Search Example:
The Binary Search Tree

\section*{Define Problem: Binary Search Tree}
- PreConditions
- Key 25
- A binary search tree.


\section*{Binary Search Tree}

All nodes in left subtree \(\leq\) Any node \(\leq\) All nodes in right subtree


\section*{Define Loop Invariant}
- Maintain a sub-tree.
- If the key is contained in the original tree, then the key is contained in the sub-tree.


\section*{Define Step}
- Cut sub-tree in half.
- Determine which half the key would be in.
- Keep that half.


If key \(<\) root, If key \(=\) root, If key \(>\) root, then key is
in left half. then key is then key is found in right \({ }_{99}\) alf.

\section*{Algorithm Definition Completed}
\begin{tabular}{|c|c|c|}
\hline Define Problem & Define Loop Invariants & Define Measure of Progress \\
\hline Define Step & Define Exit Condition & Maintain Loop Inv \\
\hline Make Progress & \begin{tabular}{l}
Initial Conditions \\
100
\end{tabular} & Ending \\
\hline
\end{tabular}

Card Trick


\title{
Loop Invariants \\ for \\ Iterative Algorithms
}

A Third
Search Example:
A Card Trick


\section*{Loop Invariant: The selected card is one of these.}



\section*{Loop Invariant: The selected card is one of these.}


\section*{Selected column is placed in the middle}


\section*{I will rearrange the cards}


\section*{Relax Loop Invariant: I will remember the same about each column.}



\section*{Loop Invariant: The selected card is one of these.}


\section*{Selected column is placed in the middle}


\section*{I will rearrange the cards}



\section*{Loop Invariant: The selected card is one of these.}


\section*{Selected column is placed in the middle}



\section*{Ternary Search}
- Loop Invariant: selected card in central subset of cards
\[
\begin{aligned}
& \text { Size of subset }=\left\lceil n / 3^{i-1}\right\rceil \\
& \text { where } \\
& n=\text { total number of cards } \\
& i=\text { iteration index }
\end{aligned}
\]
- How many iterations are required to guarantee success?

\title{
Loop Invariants for \\ Iterative Algorithms
}

A Fourth Example:
Partitioning
(Not a search problem:
can be used for sorting, e.g., Quicksort)

\section*{The "Partitioning" Problem}

\section*{Input:}


\section*{Output:}


Problem: Partition a list into a set of small values and a set of large values.

\section*{Precise Specification}

Precondition: \(\boldsymbol{A}[p \ldots r]\) is an arbitrary list of values. \(x=\boldsymbol{A}[r]\) is the pivot.


Postcondition: \(A\) is rearranged such that \(A[p \ldots q-1] \leq A[q]=x \leq A[q+1 \ldots r]\) for some \(q\).


\section*{Loop Invariant}
- 3 subsets are maintained
- One containing values less


\section*{Loop invariant:}
1. All entries in \(A[p \ldots i]\) are \(\leq\) pivot.
2. All entries in \(A[i+1 \ldots j-1]\) are \(>\) pivot.
3. \(A[r]=\) pivot.

\section*{Maintaining Loop Invariant}
- Consider element at location j
- If greater than pivot, incorporate into '> set' by incrementing j.

- If less than or equal to pivot, incorporate into ' \(\leq\) set' by swapping with element at location \(i+1\) and incrementing both i and j .


\section*{Maintaining Loop Invariant}
\(\operatorname{Partition}(A, p, r)\)
\(1 x \leftarrow A[r]\)
\(2 \quad i \leftarrow p-1\)
3 for \(j \leftarrow p\) to \(r-1\)
do if \(A[j] \leq x\)
then \(i \leftarrow i+1\)

exchange \(A[i] \leftrightarrow A[j]\)
7 exchange \(A[i+1] \leftrightarrow A[r]\)
8 return \(i+1\)

Loop invariant:
1. All entries in \(A[p \ldots i]\) are \(\leq\) pivot.

3. \(A[r]=\) pivot.

\section*{Establishing Loop Invariant}

Loop invariant:
1. All entries in \(A[p \ldots i]\) are \(\leq\) pivot.
2. All entries in \(A[i+1 \ldots j-1]\) are \(>\) pivot.

3. \(A[r]=\) pivot.

\section*{Establishing Postcondition}
\(\operatorname{Partition}(A, p, r)\)
\(1 x \leftarrow A[r]\)
\(2 \quad i \leftarrow p-1\)
3 for \(j \leftarrow p\) to \(r-1\)
4 do if \(A[j] \leq x\)
\(5 \quad\) then \(i \leftarrow i+1\)
\(6 \quad\) exchange \(A[i] \leftrightarrow A[j]\)
7 exchange \(A[i+1] \leftrightarrow A[r]\)
8 return \(i+1\)


Loop invariant:
1. All entries in \(A[p \ldots i]\) are \(\leq\) pivot.
2. All entries in \(A[i+1 \ldots j-1]\) are \(>\) pivot.
3. \(A[r]=\) pivot.

\section*{Establishing Postcondition}

Partition \((A, p, r)\)
\(1 x \leftarrow A[r]\)
\(2 \quad i \leftarrow p-1\)
3 for \(j \leftarrow p\) to \(r-1\)
do if \(A[j] \leq x\)
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exchange \(A[i] \leftrightarrow A[j]\)
7 exchange \(A[i+1] \leftrightarrow A[r]\)
8 return \(i+1\)


\section*{An Example}


\section*{Running Time}

Each iteration takes \(\theta(1)\) time \(\rightarrow\) Total \(=\theta(n)\)

or


\title{
More Examples of Iterative Algorithms
}

Using Constraints on Input to Achieve Linear-
Time Sorting

\section*{Recall: InsertionSort}

Insertion-Sort ( \(A\) )
1 for \(j \leftarrow 2\) to length \([A]\)
2 do \(k e y \leftarrow A[j]\)
\(\triangleright\) Insert \(A[j]\) into the sorted sequence \(A[1 \ldots j-1]\).
\(i \leftarrow j-1\)
while \(i>0\) and \(A[i]>\) key
do \(A[i+1] \leftarrow A[i]\)
\(i \leftarrow i-1\)
\(A[i+1] \leftarrow\) key
cost times
\(\begin{array}{ll}c_{1} & n \\ c_{2} & n-1\end{array}\)
\(0 \quad n-1\)
\(c_{4} \quad n-1\)
\(c_{5} \quad \sum_{j=2}^{n} t_{j}\)
\(c_{6}\)
\(c_{7}\)
\(c_{8}\)
\(\sum_{j=2}^{n}\left(t_{j}-1\right)\)
\(\sum_{j=2}^{n}\left(t_{j}-1\right)\)
\(n-1\)

Worst case (reverse order): \(t_{j}=j: \sum_{j=2}^{n} j=\frac{n(n+1)}{2}-1 \rightarrow T(n) \in \theta\left(n^{2}\right)\)

\section*{Recall: MergeSort}


\section*{Comparison Sorts}
- InsertionSort and MergeSort are examples of (stable) Comparison Sort algorithms.
- QuickSort is another example we will study shortly.
- Comparison Sort algorithms sort the input by successive comparison of pairs of input elements.
- Comparison Sort algorithms are very general: they make no assumptions about the values of the input elements.

\section*{Comparison Sorts}

InsertionSort is \(\theta\left(n^{2}\right)\).
MergeSort is \(\theta(n \log n)\).
Can we do better?

\section*{Comparison Sort: Decision Trees}
- Example: Sorting a 3-element array A[1..3]


\section*{Comparison Sort}
- Worst-case time is equal to the height of the binary decision tree.
- The height of the tree is the log of the number of leaves.
- The leaves of the tree represent all possible permutations of the input. How many are there?
\(\log (n!) \in \Omega(n \log n)\)
Thus MergeSort is asymptotically optimal.

\section*{Linear Sorts?}

Comparison sorts are very general, but are \(\Omega(n \log n)\)
Faster sorting may be possible if we can constrain the nature of the input.

\section*{Example 1. Counting Sort}
- Counting Sort applies when the elements to be sorted come from a finite (and preferably small) set.
- For example, the elements to be sorted are integers in the range [0...k-1], for some fixed integer \(k\).
- We can then create an array \(\mathrm{V}[0 \ldots \mathrm{k}-1]\) and use it to count the number of elements with each value [0...k-1].
- Then each input element can be placed in exactly the right place in the output array in constant time.

\section*{Counting Sort}
\begin{tabular}{l} 
Input: \\
\\
Output: \\
\hline 0
\end{tabular} 0
- Input: N records with integer keys between [0...k-1].
- Output: Stable sorted keys.
- Algorithm:
- Count frequency of each key value to determine transition locations
- Go through the records in order putting them where they go.

\section*{CountingSort}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline Input: & & 0 & 0 & 1 & 3 & & & 3 & 1 & 0 & 2 & & 0 & 1 & 1 & 2 & 2 & 2 & & 1 \\
\hline Output: & 0 & 0 & 0 & 0 & 0 & 1 & 1 & & (1) & 1 & 1 & & 1 & & & & & & & \\
\hline Index: & 0 & 1 & 2 & & 4 & 5 & 6 & 7 & 8 & 9 & 10 & & 12 & 13 & 131 & & & & & \\
\hline
\end{tabular}

Stable sort: If two keys are the same, their order does not change.
Thus the \(4^{\text {th }}\) record in input with digit 1 must be the \(4^{\text {th }}\) record in output with digit 1 .

It belongs at output index 8, because 8 records go before it ie, 5 records with a smaller digit \& 3 records with the same digit

Count These!

\section*{CountingSort}

Input:


\(N\) records. Time to count? \(\Theta(\mathrm{N})\)

\section*{CountingSort}

Input:
Output:
Index:
\begin{tabular}{|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|l|}
\hline 1 & 0 & 0 & 1 & 3 & 1 & 1 & 3 & 1 & 0 & 2 & 1 & 0 & 1 & 1 & 2 & 2 & 1 & 0 \\
\hline & & & & & & & & & & & & & & & & & & \\
\hline 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 & 13 & 14 & 15 & 16 & 17 & 18 \\
\hline
\end{tabular}

Value v:
\# of records with digit v : \# of records with digit < v:

N records, k different values. Time to count?

\(\Theta(\mathrm{k})\)

\section*{CountingSort}

\section*{Input:
Output:}

\# of records with digit < v: \(-0 \quad \triangle_{5} \quad 14\)
\(=\) location of first record with digit v .

\section*{CountingSort}


Algorithm: Go through the records in order putting them where they go.

\section*{Loop Invariant}
- The first \(i-1\) keys have been placed in the correct locations in the output array
- The auxiliary data structure \(v\) indicates the location at which to place the \(i^{\text {th }}\) key for each possible key value from [1..k-1].

\section*{CountingSort}


Algorithm: Go through the records in order putting them where they go.

\section*{CountingSort}


Algorithm: Go through the records in order putting them where they go.

\section*{CountingSort}


Algorithm: Go through the records in order putting them where they go.

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\section*{CountingSort}


Algorithm: Go through the records in order putting them where they go.

\section*{CountingSort}


Tatrad \(=\Theta(\mathrm{N} \nsucc \mathrm{k})\)

\section*{Example 2. RadixSort}

\section*{Input:}
- A of stack of \(N\) punch cards.
- Each card contains digits.
- Each digit between [0...k-1]

Output:
- Sorted cards.

Digit Sort:
- Select one digit
- Separate cards into k piles based on selected digit (e.g., Counting Sort). 243

Stable sort: If two cards are the same for that digit, their order does not change.

\section*{RadixSort}
\begin{tabular}{ll}
344 & \\
125 & \\
333 & Sort wrt which \\
134 & digit first? \\
224 & \\
334 & The most \\
143 & significant. \\
225 & \\
325 & \\
243 &
\end{tabular}


Sort wrt which digit Second?

The next most significant.

All meaning in first sort lost.

\section*{RadixSort}
\begin{tabular}{|c|c|c|c|c|}
\hline 344 & & 3313 & & 224 \\
\hline 125 & & 143 & & 125 \\
\hline 333 & Sort wrt which & 243 & Sort wrt which & 225 \\
\hline 134 & digit first? & 344 & digit Second? & 325 \\
\hline 224 & & 134 & & 333 \\
\hline 334 & The least & 224 & The next least & 134 \\
\hline 143 & significant. & 334 & significant. & 334 \\
\hline 225 & & 125 & & 143 \\
\hline 325 & & 225 & & 243 \\
\hline 243 & & 325 & & 344 \\
\hline
\end{tabular}

\section*{RadixSort}
\begin{tabular}{|c|c|c|c|c|}
\hline 344 & & 333 & & 224 \\
\hline 125 & \multirow{4}{*}{Sort wrt which digit first?} & 143 & \multirow{4}{*}{Sort wrt which digit Second?} & 125 \\
\hline 333 & & 243 & & 225 \\
\hline 134 & & 344 & & 325 \\
\hline 224 & & 134 & & 333 \\
\hline 334 & \multirow[t]{5}{*}{The least significant.} & 224 & \multirow[t]{5}{*}{The next least significant.} & 134 \\
\hline 143 & & 334 & & 334 \\
\hline 225 & & 125 & & 143 \\
\hline 325 & & 225 & & 243 \\
\hline 243 & & 325 & & 344 \\
\hline
\end{tabular}

\section*{RadixSort}


\section*{RadixSort}
\begin{tabular}{|c|c|c|c|}
\hline 224 & 1) & 125 & \\
\hline 125 & & 134 & \\
\hline 225 & Is sorted wrt & 143 & Is sorted wrt \\
\hline 325 & first i digits. & & first i+1 digits. \\
\hline 333 & & \[
\begin{array}{ll}
2 & 24 \\
2 & 25
\end{array}
\] & \\
\hline 134 & & & \\
\hline 334 & \(t\) & 243 & These are in the \\
\hline 143 & 2 & 325 & correct order \\
\hline 243 & Sort wrt i+1st & 333 & because was sorted \& \\
\hline 344 & digit. & 334 & stable sort left sorted \\
\hline & & 344 & \\
\hline
\end{tabular}

\section*{Loop Invariant}
- The keys have been correctly stable-sorted with respect to the \(i-1\) least-significant digits.

\section*{Running Time}
```

RADIX-SORT $(A, d)$
for $i \leftarrow 1$ to $d$
do use a stable sort to sort array $A$ on digit $i$

```

Running time is \(\Theta(d(n+k))\)
Where
\(d=\#\) of digits in each number
\(n=\#\) of elements to be sorted
\(k=\#\) of possible values for each digit

\section*{Example 3. Bucket Sort}
- Applicable if input is constrained to finite interval, e.g., [0...1).
- If input is random and uniformly distributed, expected run time is \(\Theta(n)\).

\section*{Bucket Sort} insert \(A[i]\) into list \(B[\lfloor n \cdot A[i]\rfloor]\)


\section*{Loop Invariants}
- Loop 1
- The first \(i-1\) keys have been correctly placed into buckets of width \(1 / n\).
- Loop 2
- The keys within each of the first \(i-1\) buckets have been correctly stable-sorted.

\section*{PseudoCode}

Bucket-Sort \((A, n)\)
for \(i \leftarrow 1\) to \(n\)
do insert \(A[i]\) into list \(B[\lfloor n \cdot A[i]\rfloor] \quad-\Theta(1)\)
for \(i \leftarrow 0\) to \(n-1\)
do sort list \(B[i]\) with insertion sort \(-\Theta(1) \times n\)
concatenate lists \(B[0], B[1], \ldots, B[n-1] \longleftarrow \Theta(n)\) return the concatenated lists
\(\Theta(n)\)

\section*{Examples of Iterative Algorithms}
- Binary Search
- Partitioning
- Insertion Sort
- Counting Sort
- Radix Sort
- Bucket Sort
-Which can be made stable?
- Which sort in place?
-How about MergeSort?

\section*{End of Iterative Algorithms}```

